# Wenxuan Xu

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### Education

Dartmouth College	2024/09 – 2026/06 (Expected)
<ul><li>MS, Computer Science with Concentration on Digital Arts</li><li>Courses: Rendering Algorithm, 3D Digital Modeling, Computer Vision, etc.</li></ul>	Hanover, NH, USA
<ul> <li>University of Liverpool (Xi'an Jiaotong-Liverpool University)</li> <li>BS, Computer Science</li> <li>GPA 3.78/4.00, First Class Honors, Dual Degree, University Academic Excellence Award</li> <li>A Courses: Computer Graphics, Operating Systems, Computer Networks and 19 others</li> </ul>	2020/09 – 2024/07 Liverpool, UK   Suzhou, China
Publication	
<ul> <li>[1] [IEEE VR' 25] Wenxuan Xu, Yushi Wei, Xuning Hu, Wolfgang Stuerzlinger, Yuntao Wa Ray Pointer Landing Poses in VR Using Multimodal LSTM-Based Neural Networks"</li> <li>[2] [IEEE VR' 25] Xuning Hu*, Wenxuan Xu*, Yushi Wei, Zhang Hao, Jin Huang, Hai-N Target Selection in VR by Integrating Proximity-Based Feedback Types and Modalities" (C</li> <li>[1] [ISMAR' 24] Xuning Hu, Xinan Yan, Yushi Wei, Wenxuan Xu, Yue Li, Yue Liu, Hai-Ni of Spatial Constraints and Curvature for 3D Piloting in Virtual Environments"</li> </ul>	Ning Liang. "Optimizing Moving o-first author)
Research Experience	
<ul> <li><u>VVISE Lab</u>, Simon Fraser University</li> <li>Research Intern, advised by <u>Prof. Wolfgang Stuerzlinger</u></li> <li>Enhancing objects selection and manipulation in VR.</li> </ul>	2023/09 - 2024/09

#### Pervasive HCI Group, Tsinghua University

Research Intern, advised by <u>Prof. Yuntao Wang</u>Utilizing AI to augment human abilities in VR.

X-CHI Lab, the Hong Kong University of Science and Technology (Guangzhou) 2022/07 – Present Research Intern, advised by Prof. Hai-Ning Liang

• Modelling user behavior (Fitts' and Steering Task) in VR environments.

• Exploring gaze-pinch based text entry input methods on T9 Layout Keyboard to improve typing accuracy.

### Projects

Physically-Based Path Tracer | C++, Physical Based Rendering

- Developed a production-quality path tracer supporting **global illumination**, **caustics**, **and physically-based materials**, implementing **photon mapping** and **final gathering** for accurate light transport simulation
- Engineered an extensible material system with physically-based **BRDFs** (Blinn-Phong, conductors, diffuse) and **importance sampling**, achieving realistic rendering of metals, glass, and textured surfaces
- Implemented advanced rendering techniques including **Multiple Importance Sampling (MIS)**, **Next Event Estimation** (**NEE**), and Russian Roulette path termination, reducing noise by 60% compared to naive path tracing
- Optimized rendering performance through **BVH acceleration structure** and multi-threading, achieving 6.42x speedup in ray-triangle intersection tests and 3.54x overall performance improvement

Predicting Ray Pointer Landing Poses in VR Using Multimodal LSTM-NN | C#, Unity, Keras 2023/08 – 2024/09
 Designed and implemented a novel VR interaction framework using Unity and Meta Quest Pro, collecting comprehensive multimodal data (head, eye, and hand movements) across 72,000 trials for Fitts' Law selection tasks

- Engineered an end-to-end ML pipeline combining **I-VDT** gaze analysis with **LSTM** neural networks, extracting behavioral features (rotational amplitude, velocity profiles) to predict ray-casting trajectories in VR selection tasks
- Achieved breakthrough performance with **1.9x accuracy improvement and 3.5x higher hit rates** over traditional kinematic methods, while maintaining **robust cross-participant generalization**, leading to publication in **IEEE VR '25**

2D Roguelike Game Development | (C#, Unity)

2023/08 - Present

2024/09 - 2024/12

- Developed a fast-paced 2D rogue-like game where players pilot diverse combat ships against waves of enemies, implementing multiple weapon systems and survival mechanics using Unity's 2D framework
- Engineered efficient game systems using **object pooling** for projectiles and enemies, **reducing memory allocation**, while implementing **A**<sup>\*</sup> **pathfinding** for intelligent enemy behavior and obstacle avoidance
- Architected robust game architecture using **design patterns (Singleton, Observer)** and Unity Events for game state management, coupled with **JSON-based data persistence** for player progression tracking

## Skills

Programming Languages and Tools: C#, C++, Python, Unity, SPSS, Maya, Meta Interaction SDK, Git Tech and Soft Skills: Physical Based Rendering, VR development, User Study Design, Eye-Tracking Data Analysis Algorithm

# **Extra-Curriculum Experience**

Student Volunteer 24th IEEE International Symposium on Mixed and Augmented Reality (ISMAR)	
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Student Volunteer 7th IEEE International Conference on Artificial Intelligence and Virtual Reality (AIVR)	
<u>GMTK 2023 Game Jam</u>	2023/07
<u>Tencent Timi Studio &amp; The Third Building Game Jam</u>	2023/11